

When is the stiffness matrix an M-matrix?

Def: $A \in \mathbb{R}^{n \times n}$ is said to be an M-matrix if $\exists B \in \mathbb{R}^{n \times n}$,

$$B_{ij} \geq 0 \quad \exists s \geq \text{largest eigenvalue of } B \quad \text{s.t.} \quad A = s\mathbb{1} - B.$$

Let \mathcal{T}_h be a triangulation of $\Omega \in \mathbb{R}^2$, $H_h \subseteq H^1(\Omega)$ a subspace of piecewise linear functions on \mathcal{T}_h with basis of hat functions $\{\phi_1, \dots, \phi_n\}$.

Let

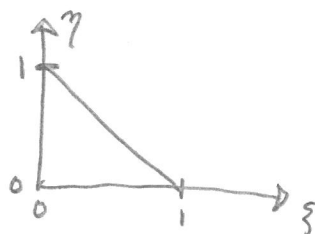
$$A_{ij} = \int_{\Omega} \nabla_x \phi_i \cdot \nabla_x \phi_j \, dx.$$

be the associated stiffness matrix.

Lemma: If $\forall T \in \mathcal{T}_h$ the interior angles are acute, then $A = (A_{ij})$ is an M-matrix.

Proof: We assemble A from the local stiffness matrices A_T .

Recall the local basis functions and their gradients on the reference triangle



$$\begin{aligned} \bar{\phi}_1(\xi, \eta) &= 1 - \xi - \eta & \nabla_{(\xi, \eta)} \bar{\phi}_1 &= \begin{pmatrix} -1 \\ -1 \end{pmatrix} \\ \bar{\phi}_2(\xi, \eta) &= \xi & \nabla_{(\xi, \eta)} \bar{\phi}_2 &= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ \bar{\phi}_3(\xi, \eta) &= \eta & \nabla_{(\xi, \eta)} \bar{\phi}_3 &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{aligned}$$

Since $\nabla_x = H^{-T} \nabla_{(\xi, \eta)}$ for some H , the local stiffness matrix is then

$$(A_T)_{ij} = \int_T \nabla_x \phi_i \cdot \nabla_x \phi_j = (\nabla_{(\xi, \eta)} \bar{\phi}_i) H^{-T} H^{-T} (\nabla_{(\xi, \eta)} \bar{\phi}_j) \text{Area}(T)$$

The diagonal entries $(A_T)_{ii}$ are > 0 .

We show that the off-diagonal entries A_{ij} are ≤ 0 :

As A_T is symmetric, it suffices to prove this for $j > i$.

We first express the conditions on the angles of T in a more convenient form: let p_0, p_1, p_2 be the vertices of T and

$$\angle(\overline{p_0 p_1}, \overline{p_0 p_2}) \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right). \text{ Then}$$

$$(0,1] \ni \cos(\angle(\overline{p_0 p_1}, \overline{p_0 p_2})) = \frac{(p_0 - p_1) \cdot (p_2 - p_0)}{\|p_0 - p_1\| \|p_2 - p_0\|}, \text{ or}$$

$$(p_0 - p_1) \cdot (p_2 - p_0) = \begin{pmatrix} H_{21} \\ H_{11} \end{pmatrix} \cdot \begin{pmatrix} H_{22} \\ H_{12} \end{pmatrix} = H_{11} H_{12} + H_{21} H_{22} > 0 \quad (*)$$

Similarly, from $\angle(\overline{p_1 p_2}, \overline{p_1 p_0}) \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$, we obtain

$$\begin{aligned} 0 &< (p_2 - p_0 + p_0 - p_1) \cdot (p_0 - p_1) = (p_2 - p_0)(p_0 - p_1) + \|p_0 - p_1\|^2 \\ &= \begin{pmatrix} -H_{12} \\ -H_{22} \end{pmatrix} \cdot \begin{pmatrix} H_{11} \\ H_{21} \end{pmatrix} + \|p_0 - p_1\|^2 = -H_{11} H_{12} - H_{21} H_{22} + H_{11}^2 + H_{21}^2 \quad (**) \end{aligned}$$

Also recall the formula for the inverse of a 2×2 matrix:

$$H^{-T} = \frac{1}{\det H} \begin{pmatrix} H_{22} & -H_{21} \\ -H_{12} & H_{11} \end{pmatrix}$$

We now check that $(A_T)_{ij} < 0$ for $j > i$:

$$\bullet \begin{pmatrix} 1 \\ 0 \end{pmatrix} H^{-1} H^{-T} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \left(\frac{1}{\det H}\right)^2 \begin{pmatrix} H_{22} \\ -H_{12} \end{pmatrix} \cdot \begin{pmatrix} -H_{21} \\ H_{11} \end{pmatrix} = -\left(\frac{1}{\det H}\right)^2 (H_{11} H_{12} + H_{21} H_{22}) < 0 \text{ by } (*)$$

$$\bullet \begin{pmatrix} -1 \\ -1 \end{pmatrix} H^{-1} H^{-T} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \left(\frac{1}{\det H}\right)^2 \begin{pmatrix} -H_{22} + H_{21} \\ H_{12} - H_{11} \end{pmatrix} \cdot \begin{pmatrix} -H_{21} \\ H_{11} \end{pmatrix} \\ = \left(\frac{1}{\det H}\right)^2 (-H_{11}^2 - H_{21}^2 + H_{11} H_{12} + H_{21} H_{22}) < 0$$

$$\bullet \begin{pmatrix} -1 \\ -1 \end{pmatrix} H^{-1} H^{-T} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \left(\frac{1}{\det H}\right)^2 \begin{pmatrix} -H_{22} + H_{21} \\ H_{12} - H_{11} \end{pmatrix} \cdot \begin{pmatrix} H_{22} \\ -H_{12} \end{pmatrix} = -\left(\frac{1}{\det H}\right)^2 \begin{pmatrix} H_{12}^2 + H_{22}^2 \\ -H_{11} H_{12} \\ -H_{21} H_{22} \end{pmatrix} < 0$$

$\Rightarrow (A_T)_{ij} < 0$ for $i \neq j \Rightarrow A_{ij} \leq 0$ for $i \neq j$. The assertion follows with $s = \max A_{ii}$. \square