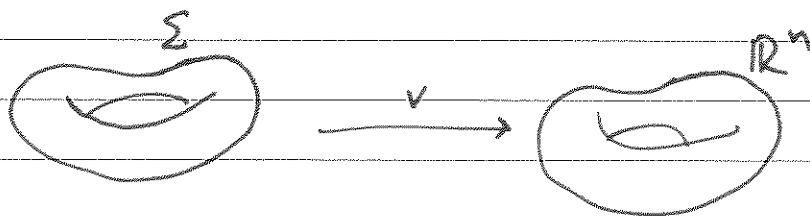


Variational Methods for PDEs Final Lecture

Nash: Def: (Σ, g) Riemannian Manifold
 "n-dim surface" \uparrow metric



v short if the induced way of measuring lengths on Σ is $\leq g$

More precisely:

$$\left[v^* (\text{euclidean metric}) \right]_{ij} := (\partial_i \bar{v}) \cdot (\partial_j \bar{v})$$

\uparrow
scalar product for tangent vectors on Σ

$$\text{If } \sum_{i,j} g_{ij} \xi_i \xi_j \geq \sum_{i,j} [v^*(\text{eucl})]_{ij} \xi_i \xi_j \quad \forall \xi$$

$\Rightarrow v$ is short.

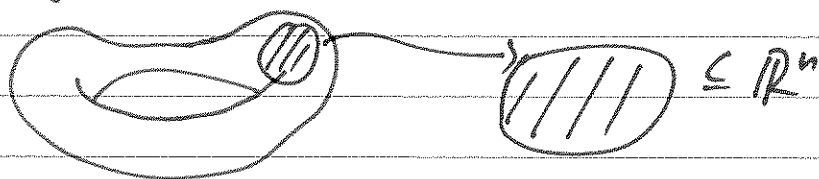
Thm :: (Nash-Kuiper) (Σ, g) smooth, without boundary, of dim n

$\bullet v: \Sigma \rightarrow \mathbb{R}^N$, C^∞ , short, $N \geq n+2$
 s.t. Jacobian is injective (immersion)

$\Rightarrow \forall \epsilon > 0 \exists$ isometric C^1 -immersion $u: \Sigma \rightarrow \mathbb{R}^N$ s.t.
 $\|u-v\|_{C^0} < \epsilon$.

Corollary: Any smooth n -dimensional Riemannian manifold has a C^1 -isometric immersion in \mathbb{R}^{2n} .

While the ~~the~~ statement of principal interest of these results are geometric, the underlying techniques are about nonlinear pdes



g isometric to $v^\#$ (eucl.) = $(\partial_i \vec{v}) \cdot (\partial_j \vec{v})$

\Leftrightarrow Find \vec{v} st
 $\mathbb{R}^n \supset \mathcal{D} \rightarrow \mathbb{R}^N$

$$\left[\begin{array}{l} (\partial_i \vec{v}) \cdot (\partial_j \vec{v}) = g_{ij} \end{array} \right]$$

$\frac{n(n+1)}{2}$ equations
for N unknowns

Claim: $\exists C^1$ solution for $N = n+2$

References: C de Lellis • Masterpieces of John F. Nash
 • Nash's nonlinear iteration

The theorem will follow from:

Key proposition (NNI, 2.1)

• (Σ, g) as above

• $z: \Sigma \rightarrow \mathbb{R}^N$ C^0 short immersion

$\Rightarrow \forall \eta, \delta > 0 \exists C^0$ short $z_1: \Sigma \rightarrow \mathbb{R}^N$ s.t.

$\|z - z_1\|_{C^0} \leq \eta \leftarrow z_1$ is close to z

almost satisfied $\rightarrow \|g - z_1^\#$ (eucl.) $\|_{C^0} \leq \delta$

$\|Dz_1 - Dz\|_{C^0} \leq C \sqrt{\|g - z_1^\#$ (eucl.) $\|_{C^0}} \quad \exists C = C(\Sigma)$

(If z injective $\Rightarrow z_1$ injective)

$Dz_1 - Dz$
is not
too big

This is what we will show.

Proof of Thm using key proposition:

Let ~~v~~ $v =: v_0$. May assume v_0 strictly short
i.e. " $<$ " instead of " \leq ".

Apply proposition with $z = v_0$ and $\eta = \frac{\epsilon}{4}$, $\delta = \frac{1}{4}$.

\Rightarrow Get $z_1 = v_1$, which is "more isometric" in the sense of the proposition.

Iterate $z = v_j$, $\eta = \frac{\epsilon}{2^{j+2}}$, $\delta = \frac{1}{4^{j+1}} \longrightarrow z_1 = v_{j+1}$

$\nwarrow \nearrow$
i.e. apply proposition with smaller and smaller η 's and δ 's.

Take $\lim_{j \rightarrow \infty} v_j =: u$

From Δ -inequality: $u = \lim_{j \rightarrow \infty} v_0 + (v_1 - v_0) + (v_2 - v_1) + (v_3 - v_2) + \dots$

$$\|v_1 - v_0\| \leq \eta = \frac{\epsilon}{2^2}$$

$$\|v_2 - v_1\| \leq \eta = \frac{\epsilon}{2^3} \quad \Rightarrow \quad \|v_{j+1} - v_j\|_{C^0} \leq \frac{\epsilon}{2^{j+1}}$$

\Rightarrow u exists (because the series cges)

$$\|Dv_{j+1} - Dv_j\|_{C^0} \leq C(\Sigma) \sqrt{\|g - v_j^\#(\text{eucl.})\|_{C^0}} \leq C\delta^{1/2}$$

\Rightarrow convergence is in C^1 , not just in $C^0 \rightarrow 0$

$$(\partial_i \vec{u}) \cdot (\partial_j \vec{u}) \longleftarrow v_k^\#(\text{eucl.}) = (\partial_i \vec{v}_k) \cdot (\partial_j \vec{v}_k) \xrightarrow[k \rightarrow \infty]{} g$$

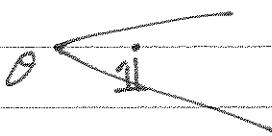
(because C^1 -cges)

\Rightarrow $(\partial_i u) \cdot (\partial_j u) = g$ have solved eqn. \square

Local ("analysts'") statement of key proposition

Define $\mathcal{L}_r := \{A \in \mathbb{R}_{\text{sym}}^{n \times n} : \left\| \frac{A}{\frac{1}{n} \text{tr} A} - \mathbb{1} \right\| < r\}$

cone of symmetric
 $n \times n$ matrices near $\mathbb{1}$



Key prop: $\exists r_0 = r_0(n)$ s.t.: If $U \subset \mathbb{R}^n$ odd
simply connected (no holes) open domain
• $g \in C^\infty(\bar{U})$ smooth metric
• $z: \bar{U} \rightarrow \mathbb{R}^N$ C^∞ smooth, short s.t.
 $g - z^*(\text{eucl.}) \in \mathcal{L}_{r_0} \forall x \in \bar{U}$

$\implies \forall \eta, \delta > 0 \exists$ smooth short map $z_1: \bar{U} \rightarrow \mathbb{R}^N$ s.t.
 $g - z_1 \in \mathcal{L}_{r_0} \forall x \in \bar{U}$
and $\|z - z_1\|_{C^0} \leq \eta$
 $\|g - z_1^*(\text{eucl.})\|_{C^0} \leq \delta$
 $\|Dz - Dz_1\|_{C^0} \leq M_U \sqrt{\|g - z_1^*(\text{eucl.})\|_{C^0}}$

In order to prove this: (NNT, 2.4)

Lemma 2.4: Let $S_+^{n \times n}$ = set of pos. def. symmetric
 $n \times n$ matrices

$\implies \exists$ neighborhood W of $\mathbb{1}$ and $N(n) = \frac{n(n+1)}{2}$
unit vectors $v_k \in \mathbb{R}^N$ s.t.

any $A \in W$ can be written as

$$A = \sum_{k=1}^N \lambda_k(A) v_k \otimes v_k$$

where $\lambda_k: W \rightarrow \mathbb{R}$ linear in A and $\lambda_k(A) \geq \rho_0(n) > 0$

Proof of analysts' key proposition (\Rightarrow Theorem)

$$z^*(\text{eucl.}) = Dz^T Dz$$

By assumption $g - Dz^T Dz \in \mathcal{C}^r_0 \leftarrow$ all of these matrices > 0
 $\Rightarrow g - Dz^T Dz \geq 2\gamma \mathbb{1} \quad \exists \gamma > 0.$

wlog $\gamma \leq \delta$, Let $h = g - Dz^T Dz - 2\gamma \mathbb{1} \in \mathcal{C}^r_0$

From lemma: $h(x) = \sum_{k=1}^N a_k^2(x) v_k \otimes v_k$ because λ linear in h

Define improvement of z : \bar{z}

$$D\bar{z}^T D\bar{z} \approx Dz^T Dz + h, \quad \text{This shrinks the error in } z^*(\text{eucl.}) = g$$

The rigorous formulation is:

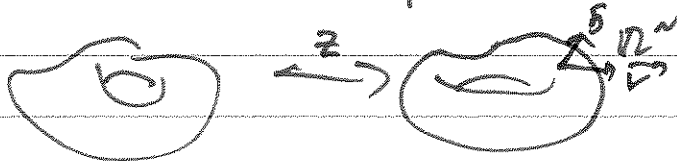
Proposition: Under the above assumptions

$\exists \bar{z} \in C^\infty(\bar{U} \rightarrow \mathbb{R}^n)$ short st.

$$\|\bar{z} - z\|_{C^0} < \tilde{\eta}, \quad \|D\bar{z}^T D\bar{z} - g - \sum_{i=1}^N a_i^2 v_i \otimes v_i\|_{C^0} \leq \tilde{\delta}$$

$$\|D\bar{z} - Dz\|_{C^0} \leq M_N \|a_i\|_{C^0}$$

Proof: $\bar{z}(x) = z(x) + z_p(x)$ where z_p is defined as follows



$N \geq n+2$
 \Rightarrow Can find 2 normal vectors which are $\perp \forall x.$

$$\|v\| = \|b\| = 1 \quad \forall x$$

$$\text{Define } z_p = \frac{a(x)}{\lambda} (v(x) \cos(\angle v, x) + b(x) \sin(\angle v, x))$$

λ chosen to make estimates work. $\gg 1$.

$\Rightarrow z - \bar{z}$ small for $\lambda \gg 1$.

$$\|D\bar{z} - Dz\| \leq C \|a\| \checkmark$$

$$D\bar{z} = Dz + Dz_p$$

$$D\bar{z}^T D\bar{z} = (Dz + Dz_p)^T (Dz + Dz_p)$$

$$= \underbrace{Dz^T Dz}_{\neq 0} + \underbrace{Dz^T Dz_p}_{\neq 0} + \underbrace{Dz_p^T Dz}_{\neq 0} + \underbrace{Dz_p^T Dz_p}_{\text{leading term}}$$

Key observation :

because (rotation) z_p
~~area~~ were added in
normal direction. \square