

Variational Methods: Lecture 1 (With Heiko)

Recall:

- $W^{1,p}(\Omega) = \{f \in L^p(\Omega) : \partial_x f \in L^p(\Omega)\}$
we could consider $\Omega \subseteq \mathbb{R}^n$ (usually bounded).

- Functionals $E(u) = \int_{\Omega} F(x, u, \nabla u) dx$
on a suitable topological space $\ni U$

Previously we have seen a discussion of minimizers of E

E.g.: To find equilibrium/ground state of physical system

- Find a minimal surface = surface of minimal area given boundary
 - Find geodesics
 - Find best approximation of data by a function
- Soap bubbles → (points to minimal surface)
- Length minimising curve → (points to geodesics)

General Set up I:

Consider V a Banach space, the dual space V^* and $E: V \rightarrow \mathbb{R}$ a functional

↑
Assume Fréchet differentiable

DE derivative: $\langle v, DE(u) \rangle := \frac{d}{d\varepsilon} E(u + \varepsilon v) \Big|_{\varepsilon=0}$
 $v \rightarrow v^*$

directional derivative in direction $v \in V$
(Gateaux derivative)

2)

• Basic test for u being a minimizer:
is $DE(u) = 0$?

• u 's that satisfy this are critical points

? Question: Do there exist minimizers / critical points?

↳ Are they unique?

↳ Are there solutions to the EL-equation?

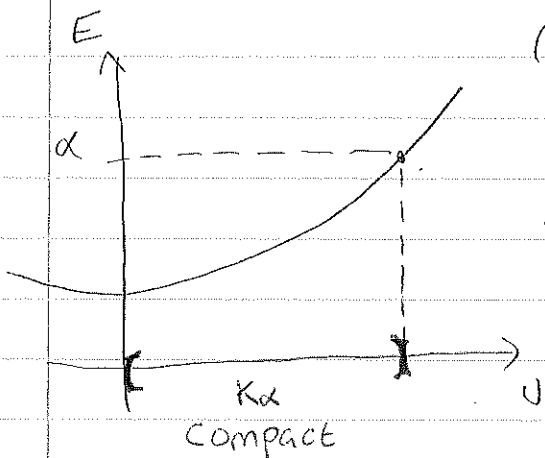
($DE(u) = 0$ is the Euler-Lagrange equation)

Theorem: (most general set up)

• M is a topological Hausdorff space

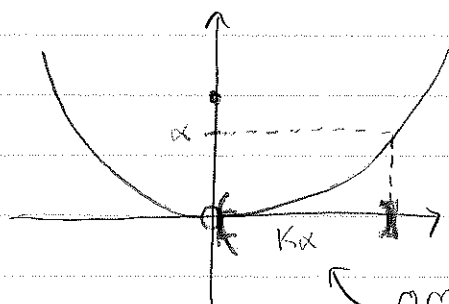
• $E: M \rightarrow \mathbb{R} \cup \{\infty\}$ satisfies,

$\forall \alpha \in \mathbb{R}: K_\alpha = \{u \in M: E(u) \leq \alpha\}$ is compact
(or sequentially compact)



$\Rightarrow E$ is bounded uniformly from below on M and attains its minimum

Counter example: 1) Consider $E(x) = x^2$, $x \in [-1, 1] \setminus \{0\}$
where $E(0) = 1$

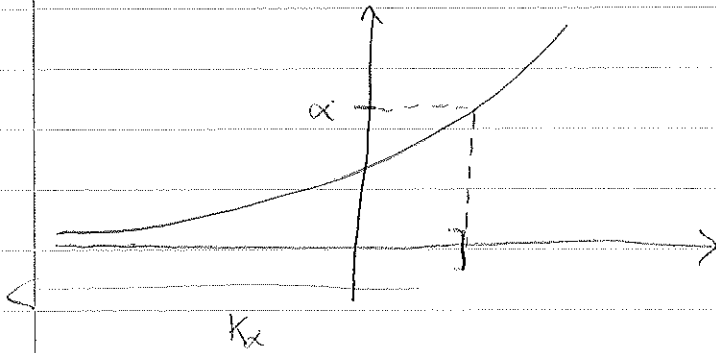


half open interval, not compact

omits 0 \Rightarrow

3)

2) $E(x) = e^x, x \in \mathbb{R}$



K_α is an unbounded interval \Rightarrow not compact.

in this example, $\inf E = 0$, no minimizers.

Proof of Theorem: Assume $E \neq \infty$ (since we are seeking minimizers)

Let $\alpha_0 = \inf_M E \geq -\infty$ (*)

Let $\{\alpha_m\}_{m \in \mathbb{N}}$ strictly decreasing $\alpha_m \searrow \alpha_0$

$K_m := K_{\alpha_m}$ compact (by our assumption)
 \hookrightarrow also $K_m \supset K_{m+1} \supset K_{m+2} \supset \dots$

By compactness $\bigcap_m K_m \neq \emptyset \Rightarrow u \in \bigcap_m K_m$

i.e: $E(u) \leq \alpha_m \forall m$ \leftarrow

as $m \rightarrow \infty: E(u) \leq \alpha_0$

By (*) $E(u) = \alpha_0$ and u is a minimizer

□

For PDES our space M is often a subset of a vector space of functions, and instead of assumptions on sublevel sets K_α it is easier to check the following sufficient conditions:

4)

Theorem: For V a reflexive Banach Space
(i.e.: $W^{1,p}(\Omega)$, $p \neq 1, \infty$)

• With $M \subset V$ weakly closed

• $E: M \rightarrow \mathbb{R} \cup \{\infty\}$ such that

1) coercivity: $E(U) \rightarrow \infty$ as $\|U\|_V \rightarrow \infty$

2) $\forall U \in M \forall \{U_m\} \subset M$ with

$U_m \rightarrow U$ weakly then

Lower semi continuity \rightarrow

$$E(U) \leq \liminf_{m \rightarrow \infty} E(U_m)$$

Then E is bounded from below and there exists a minimizer

Examples:

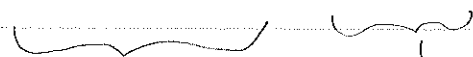
1) $E(U) = \|U\|_{W^{1,p}(\Omega)}^p$ or $\|U\|_{W^{1,p}(\Omega)}$ $\forall p \in (1, \infty]$

more generally,

$$E(U) = \|U\|_V \text{ for } V \text{ Banach space}$$

2) $E(U) = \frac{1}{p} \int_{\Omega} |\nabla U|^p - \int_{\Omega} F U$, $p \in (1, \infty)$
 $E: W_0^{1,p}(\Omega) \rightarrow \mathbb{R}$

$$= \frac{1}{p} \|U\|_{W^{1,p}(\Omega)}^p - \int_{\Omega} F U$$



this term satisfies

2) in the above thm

$$\rightarrow \text{if } F \in W_0^{1,p}(\Omega)^* = W^{-1,q}(\Omega)$$

For $\frac{1}{p} + \frac{1}{q} = 1$

(F is a linear functional)

then this term also

satisfies 2)

$$\text{Indeed, } \langle F, U \rangle = \int_{\Omega} F U$$

$$\lim_{m \rightarrow \infty} \langle F, U_m \rangle = \int_{\Omega} F U \text{ if } U_m \rightarrow U$$

5)

Thus $E(u)$ satisfies condition 2).

For condition 1) we need to show

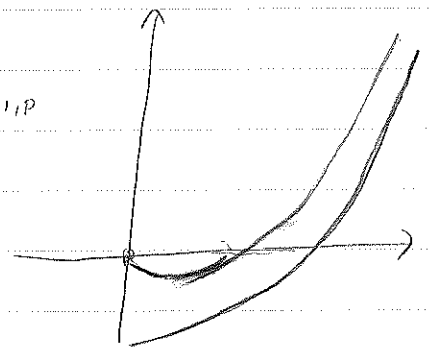
$$E(u) \rightarrow \infty \text{ as } \|u\|_{W^{1,p}(\Omega)} \rightarrow \infty$$

↳ Idea: $x^p - cx \rightarrow \infty$ as $x \rightarrow \infty$ if $p > 1$

$$E(u) = \frac{1}{p} \|u\|_{W^{1,p}}^p - \int_{\Omega} F u$$

$$\geq \frac{1}{p} \|u\|_{W^{1,p}}^p - \underbrace{\|F\|_{W^{1,p}^*}}_{= C < \infty} \|u\|_{W^{1,p}}$$

$$= \frac{1}{p} \|u\|_{W^{1,p}}^p - C \|u\|_{W^{1,p}} \quad (-)$$



$\geq \alpha \|u\|_{W^{1,p}}^p - C \quad (-)$ for some $\alpha, c > 0$

$\rightarrow \infty$ as $\|u\| \rightarrow \infty$

Thus 1) and 2) are satisfied and there exists a minimizer $u \in W_0^{1,p}(\Omega)$

□

What does $DE(u) = 0$, the Euler Lagrange equation look like? (for $p \geq 2$)

$$\langle DE(u), v \rangle := \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} E(u + \varepsilon v)$$

$\forall v \in W_0^{1,p}(\Omega)$

$$= \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} \frac{1}{p} \int_{\Omega} (\nabla(u + \varepsilon v))^p dx - \int_{\Omega} F(u + \varepsilon v) dx$$

6)

$$\begin{aligned}
 &= \frac{d}{d\varepsilon} \bigg|_{\varepsilon=0} \left\{ \frac{1}{P} \int_{\Omega} |\nabla U + \varepsilon \nabla V|^P dx - \int_{\Omega} F U dx - \varepsilon \int_{\Omega} F V dx \right\} \\
 &= \frac{1}{P} \int_{\Omega} |\nabla U|^P \left(\frac{\nabla U}{|\nabla U|} + \varepsilon \frac{\nabla V}{|\nabla U|} \right)^P dx - \int_{\Omega} F V dx \\
 &\quad \text{Taylor expand diff + set } \varepsilon = 0 \\
 &= \int_{\Omega} |\nabla U|^{P-2} \nabla U \cdot \nabla V dx - \int_{\Omega} F V dx
 \end{aligned}$$

Now if U is a minimizer $\Rightarrow \langle DE(U), V \rangle = 0$
 $\forall V \in W_0^{1,p}(\Omega)$

$$\int_{\Omega} |\nabla U|^{P-2} \nabla U \cdot \nabla V dx - \int_{\Omega} F V dx = 0$$

(This is the weak formulation of

$$\begin{aligned}
 -\nabla \cdot (|\nabla U|^{P-2} \nabla U) &= F & \text{in } \Omega \\
 U &= 0 & \text{on } \partial\Omega
 \end{aligned}$$

Indeed if U is sufficiently smooth, such that $|\nabla U|^{P-2} \nabla U \in W^{1,2}(\Omega)$ then we can integrate by parts:

$$-\int_{\Omega} \nabla \cdot (|\nabla U|^{P-2} \nabla U) V dx + \int_{\partial\Omega} \dots - \int_{\Omega} F V dx = 0$$

0 since $V = 0$ on $\partial\Omega$

i.e. $-\int_{\Omega} \left\{ \nabla \cdot (|\nabla U|^{P-2} \nabla U) + F \right\} V dx = 0 \quad \forall V \in W_0^{1,p}$

$$\Leftrightarrow \nabla \cdot (|\nabla U|^{P-2} \nabla U) + F = 0 \quad \text{in } (W_0^{1,p})^*$$

7)

Conclusion: $\nabla \cdot (|\nabla u|^{p-2} \nabla u) + f = 0$
 admits a solution $u \in W_0^{1,p}(\Omega)$
 \wedge
 weak

One can easily show that it is unique
 \hookrightarrow If $u_1, u_2 \in W_0^{1,p}(\Omega)$ are two solutions then,

$$\int_{\Omega} (|\nabla u_1|^{p-2} \nabla u_1 \cdot \nabla v - |\nabla u_2|^{p-2} \nabla u_2 \cdot \nabla v) - f v + f v = 0$$

Choose $v = u_1 - u_2$

$$\int_{\Omega} (|\nabla u_1|^{p-2} \nabla u_1 - |\nabla u_2|^{p-2} \nabla u_2) \cdot \nabla (u_1 - u_2) = 0$$

\forall

$$0 \leq \int_{\Omega} |\nabla (u_1 - u_2)|^p dx$$

$$\Rightarrow u_1 = u_2$$

$\Rightarrow u$ is unique \Downarrow

Another example: $\Omega \subset \mathbb{R}^n$ bounded domain

and $S \subset \mathbb{R}^n$ compact

Consider functions $u: \Omega \rightarrow \mathbb{R}^n$ such that $u(x) \in S$ a.e

Define, $W^{1,2}(\Omega, S) = \{u \in W^{1,2}(\Omega) : u(x) \in S \text{ a.e}\}$

\uparrow
 takes values in \mathbb{R}^n

Consider the energy

$$E(u) = \int_{\Omega} g_{ij}(u) \nabla u^i \cdot \nabla u^j dx$$

8)

This energy functional appears in the study of minimal \mathcal{U} hyper surfaces in a Riemann manifold: $E(u) \rightarrow \min$

The relevant M to apply our theorem is

$$M = \{ u \in W^{1,2}(\Omega, S) : u = u_0 \text{ on } \partial\Omega \}$$