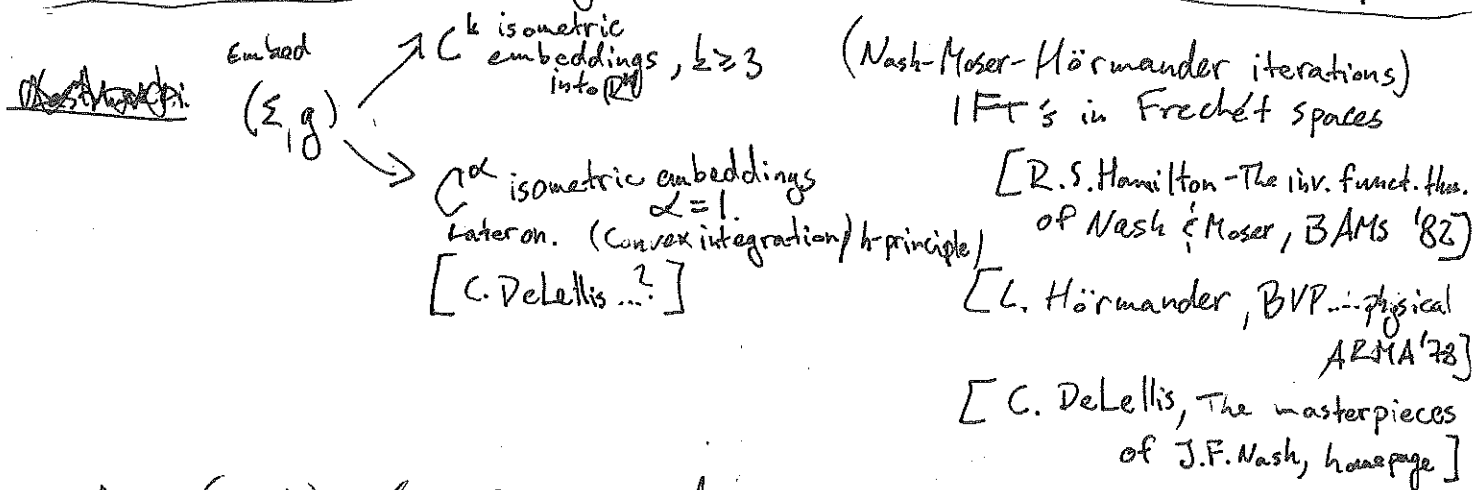


Smooth isometric embeddings & inverse fc. theorems in Frechet spaces



Thm. (Nash)  $(\Sigma, g)$  closed  $n$ -dim. Riemannian manifold with metric of class  $C^k$ ,  $k \geq 3$ ,  $n \geq 1$ ,  $N = \frac{n(3n+11)}{2}$   
 $\Rightarrow \exists$  isometric embeddings:  $\Sigma \rightarrow \mathbb{R}^N \in C^k$ .

Recall: Manifold has local coords  $(x_1, \dots, x_n)$ . Assume local patches are "nice" (balls). Only finitely many patches overlap in any given point.

Then,  $g = \sum_{i,j} g_{ij} dx_i \otimes dx_j$  is metric in local coords.  
 These are  $C^k$ .

If  $T$  is any tensor field on  $\Sigma$ : similarly define  $C^k$ -norms

$$\|T\|_{C^k} = \sup_{\text{coord. patches}} \|T_{(i_1, \dots, i_k)}\|_{C^k(\mathbb{R}^n)}$$

Why is Thm. a PDE Question?

Thm.  $\Leftrightarrow$  Find  $u: \Sigma \rightarrow \mathbb{R}^N$  embedding s.t.  $(\partial_i u) \cdot (\partial_j u) = g_{ij}$ ,  $\forall i,j$ .

invariant way of writing is:  $u^* \text{eucl}_{\mathbb{R}^n} = g$

$$\int_{\Sigma} (\partial_i u) \cdot (\partial_j u) dx_i \otimes dx_j.$$

Remark  $N$  has been lowered later by Gromov, Günther  $\leadsto N = 2n$ .

- ② Remark: Günther showed that if you work in  $C^{k,\alpha}$  spaces,  $\alpha > 0$ , then standard Banach fixed point arguments suffice
- But techniques were found to be useful: KAM theory of perturbations of integrable systems (Moser), inverse/implicit function thms in Free SP

Strategy: Linearise + Perturbation result  $\equiv$  implicit function theorem

Start with  $W_0 = (w_1, \dots, w_N)$  smooth embeddings  $\Sigma \rightarrow \mathbb{R}^N$ .

Take  $h = g - w_0^\# \text{ encl.}$  (Ideally  $h=0$ )

• If  $h$  is small, find  $u: \Sigma \rightarrow \mathbb{R}^N$  smooth embedding

find  $u^\# \text{ encl.} - w_0^\# \text{ encl.} = h$ . If we can find  $u \Rightarrow$  Result  
 $u = w(\infty)$

Consider curves of embeddings:  $[t_0, \infty) \ni t \rightarrow w(t)$

defined by  $w(t)^\# \text{ encl.} = w_0^\# \text{ encl.} + h(t) w_0^\# = w(t)$  (\*)  
 where  $h(0) = 0, h(\infty) = h$ .

$$\underbrace{\sum_{i,j} dx_i \otimes dx_j \left( \frac{\partial w}{\partial x_i} \cdot \frac{\partial \dot{w}}{\partial x_j} + \frac{\partial \dot{w}}{\partial x_i} \cdot \frac{\partial w}{\partial x_j} \right)}_{\hookrightarrow = 2 dw \otimes d\dot{w}} = \sum_{i,j} h_{ij} dx_i \otimes dx_j (**)$$

Assume that  $\dot{w}$  is orthogonal to  $w(\Sigma)$ :  $\frac{dw}{dx_j} \cdot \dot{w} = 0$  (\*\*\*)

We are going to solve (\*\*\*)  $\hat{=}$  (\*\*).

$$(***) \Rightarrow 0 = \frac{\partial}{\partial x_i} \left( \frac{\partial w}{\partial x_j} \cdot \dot{w} \right) = \frac{\partial \dot{w}}{\partial x_i} \cdot \frac{\partial w}{\partial x_j} + \dot{w} \cdot \frac{\partial^2 w}{\partial x_i \partial x_j}$$

$$\Rightarrow \text{(***)} \begin{cases} -2 \frac{\partial^2 w}{\partial x_i \partial x_j} \cdot \dot{w} = h_{ij} \\ \frac{\partial w}{\partial x_i} \cdot \dot{w} = 0 \end{cases}$$

3) It would be nice to solve (□) for  $\dot{w} = \mathcal{L} h_{ij} \Rightarrow$  ODE.

Def:  $w$  is called free if in every system of local coords., the  $n + \frac{n(n+1)}{2}$  vectors  $\frac{\partial w}{\partial x_i}(p), \frac{\partial^2 w}{\partial x_i \partial x_j}(p)$  ( $p \in \mathcal{E}, i, j \in [1 \dots n]$ ) are lin. indept.

Note:  $w$  free  $\Rightarrow w$  immersion.  
 $w$  free + injective  $\Rightarrow w$  embedding

Main Thm: Let  $w_0 : \Sigma \rightarrow \mathbb{R}^N$  be a free  $C^\infty$  embedding and let  $k \geq 3$ .  
 Then  $\exists \varepsilon_0 = \varepsilon_0(w_0), \forall h \in C^k$  with  $\|h\|_{C^3} < \varepsilon_0$ ,  
 $\exists \bar{u} : \Sigma \rightarrow \mathbb{R}^N, C^k$  embedding s.t.  $\bar{u}^\# \text{encl.} = w_0^\# \text{encl.} + h$

Since  $\varepsilon_0 = \varepsilon_0(w_0)$ , we have to find a good  $w_0$  to deduce embedding thm.

TODO: (i) Main Thm.  $\Rightarrow$  Nash's Thm. (geometric)

(ii) Proof of Main Thm. (analysis)

(1)  $\rightarrow$  (i) Fix a free  $C^\infty$  embedding  $w_0$ , strictly short w.r.t.  $g$

Fix  $\varepsilon_0$  s.t. Main thm. applies.  $(\text{encl. } (\partial_i w_0)(\partial_j w_0) - \frac{1}{2} g_{ij})$

(ii) Build a smooth  $\bar{w} : h := g - w_0^\# \text{encl.} - \bar{w}^\# \text{encl.}$   $\forall \xi \neq 0$   
 Satisfies  $\|h\|_{C^3} < \varepsilon_0$ .

(iii) Apply Main thm.  $\Rightarrow \bar{u} : \Sigma \rightarrow \mathbb{R}^N$ ; set  $u = \bar{u} \times \bar{w}$  does the job.

Note that  $(\bar{u} \times \bar{w})^\# = \bar{u}^\# + \bar{w}^\#$

[More details - DeLellis]

(4) If  $w$  is free embedding for all  $t$ , then in (□) coeff. matrix  $F$  has full rank:  $Aw = \begin{pmatrix} h \\ 0 \end{pmatrix}$ .

Thus  $AA^T$  invertible.

A soln. of (□) is given by  $\dot{w} = \underbrace{A^T(AA^T)^{-1}}_{=: \mathcal{L}(Dw, D^2w)} \begin{pmatrix} h \\ 0 \end{pmatrix}$ .

It follows that we formally have ODE:

$$\begin{aligned} \dot{w} &= \mathcal{L}(Dw, D^2w) h \\ w(t_0) &= w_0. \end{aligned}$$

Problem: Loss of derivatives;  $\dot{w}$  depends on  $Dw, D^2w$ .  
If  $w, h \in C^k \Rightarrow \mathcal{L}(\dots)h \in C^{k-2}$ .

Standard ODE theory (Cauchy-Lipschitz, Picard-Lindelöf) won't work.

Nash considers a regularized problem. Introduce a smoothing operator. Key idea - Modify ODE which can be solved.

Lemma:  $\exists$  a family  $(S_\varepsilon)_{\varepsilon \in (0,1)}$  of <sup>linear</sup> operators on  $C^k(\mathbb{R}^m)$  s.t.

(a)  $S_\varepsilon f \in C^\infty(\mathbb{R}^m)$ ,  $\forall f \in C^k$ .

(b)  $\forall r \geq s, \exists C: \|D^r S_\varepsilon f\|_{C^0} \leq C \varepsilon^{s-r} \|f\|_s$

(c)  $\forall r \geq s, \exists C: \|D^r \frac{\partial S_\varepsilon}{\partial \varepsilon} f\|_{C^0} \leq C \varepsilon^{s-r-1} \|f\|_s$ .

(d)  $\forall s > r, \exists C: \|D^r (f - S_\varepsilon f)\|_{C^0} \leq C \varepsilon^{s-r} \|f\|_s$ .

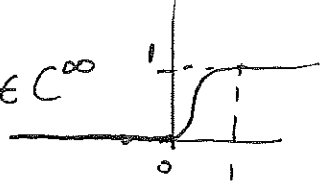
Proof:  $S_\varepsilon f(x) = \frac{1}{\varepsilon^m} \int_{\mathbb{R}^m} f(x-y) \varphi(y/\varepsilon) dy$ .  $\square$   
Fix  $\varphi \in S(\mathbb{R}^m)$ .  $\int \varphi = 1, \varphi \geq 0$ .

This Lemma extends to fcs on  $\Sigma$  and to tensor fields.

i) Regularized Problem:

$$\begin{cases} \mathcal{L}(D_w, D^2 w) = \mathcal{L}(w) \\ \dot{w} = \mathcal{L}(S_{t-t_0} w) h_w(t) \\ w(t_0) = w_0. \end{cases}$$

Will require careful choice of  $h$ . Let  $\psi \in C^\infty$



$$h_w(t) = S_{t-t_0} \left[ \psi(t-t_0) h + \int_{t_0}^t \mathcal{L} d (S_{t-\tau} w(\tau) - w(\tau)) \circ \text{div}(\tau) \psi(t-\tau) \right]$$