

13/03/20

- Abstract error analysis for spectral methods (or other non-Galerkin discretisations of weak formulations).
- Application to Allen-Cahn eqn.
- Comments about special orthogonal polynomials
- Nonlinear continuum dynamics and contact / interface problems.

PDE: $a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h \quad (*)$

FE:

Find $u_h \in U_h$ st. $(*)$. $U_h \subset U$

$V_h \subset V$

$V = \text{Dirac-}\delta\text{'s} \quad \longleftrightarrow \quad \text{Collocation}$

$V = U \quad \longleftrightarrow \quad \text{Galerkin / standard FE}$

Th^m (i) U, V ~~(Hilbert)~~ Hilbert spaces

(ii) $F: V \rightarrow \mathbb{R}$ linear and cts.

(iii) $a: X \times Y \rightarrow \mathbb{R}$ ~~bilinear~~ ^{sesquilinear} form which is

(I) cts: $|a(u, v)| \leq C \|u\|_U \|v\|_V$

injective (II) inf-sup condition: $\inf_{u \in U} \sup_{v \in V} \frac{a(u, v)}{\|u\|_U \|v\|_V} \geq \beta > 0$

surjective (III) transposed inf-sup: $\sup_{v \in V} a(u, v) > 0 \quad \forall u \in U \setminus \{0\}$

Then $\exists ! u \in U$ s.t. $a(u, v) = F(v) \quad \forall v \in V$.

Corollary Same for subspaces U_h, V_h : $a(u_h, v_h) = F(v_h) \quad \forall v_h \in V_h$

(Cea's Lemma). In this case $\|u - u_h\|_U \leq \tilde{C} \|u - \tilde{u}_h\|_U \quad \forall \tilde{u}_h \in U_h$,

$\tilde{C} = \tilde{C}(C, \beta, \beta_h)$.

Remarks: 1. If $U = V$ this generalises the Lax-Milgram theorem and the classical Cea's Lemma for coercive ~~the~~ bilinear forms a . Coercivity implies both inf-sup and transposed inf-sup conditions.

2. Cases where standard LM can't be applied for $U = V$.

(i) Helmholtz: $-\Delta u - k^2 u = f$.

(ii) Compact perturbations of coercive problems (ie. addition of lower order terms).

In this case, well posedness is equivalent to ~~the~~ inf-sup + trans inf-sup.

3. For spectral methods often $U \neq V$, $U_h \neq V_h$.

In the case of coercive a , we do not need to impose an inf-sup or coercivity condition on U_h, V_h :

$$a(u_h, u_h) \geq \alpha \|u_h\|^2 \quad \forall u_h \in U_h$$

follows from ineq. for the whole space.

For the inf-sup condition we need to check separately for subspaces since $\sup_{V_h} \leq \sup_V$ when $V_h \subset V$.

inf-sup for $U, V \not\Rightarrow$ inf-sup for U_h, V_h .

(major issue for Navier-Stokes and Stokes problems).

Stokes:
$$\begin{pmatrix} -\Delta & \nabla \\ \nabla \cdot & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}.$$

\uparrow
Zero

Proof of Th^m. See notes on webpage.

Proof of Cea's Lemma.

Denote by P_{V_h} the orthogonal projector $P: V \rightarrow V_h$,

and by $R(u)$ the operator $R: U \rightarrow V$

$$a(u, v) = (R(u), v)_V \quad \forall v \in V.$$

NOTE: R well defined. ~~by existence of R~~

eg. $a(u, v) = \int \nabla u \cdot \nabla v$, $R(u) = u$, $U, V = H_0^1$

$$Q := P_{V_h} R : U \xrightarrow{R} V \xrightarrow{P_{V_h}} V_h$$

Define $S: U_h \rightarrow V_h$ by $(S u_h, v_h)_V = a(u_h, v_h) \quad \forall u_h \in U_h, v_h \in V_h$

Claim. $S u_h = Q u_h \quad \forall u_h \in U_h.$

Pf. $(P_{V_h} R u_h, v_h)_V = (R u_h, P_{V_h} v_h)$
 $= (R u_h, v_h)$
 $= a(u_h, v_h)$ □

$$\Rightarrow S = Q|_{U_h}$$

For the RHS we ~~define~~ let $v_{0,h} \in V_h$ be st.

$$F(v_h) = (v_{0,h}, v_h)_V, \quad \forall v_h \in V_h$$

Then since $a(u, v_h) = F(v_h)$, $\forall v_h \in V_h$ we have

$$v_{0,h} = P_{V_h} R u.$$

Further, $u_h = S^{-1} P_{V_h} R u$,

where S is invertible by existence of sol^s to eqn on U_h, V_h .

Then

$$u_h - u = S^{-1} P_{V_h} R u - u \quad (*)$$

NOTE. $S^{-1} P_{V_h} R \Big|_{U_h} = I \Big|_{U_h}$

Then $(*) = (S^{-1} P_{V_h} R - I)(u - \tilde{u}_h) \quad \forall \tilde{u}_h \in U_h$

Moreover, the operator $S^{-1} P_{V_h} R - I$ is bounded so

$$\|u - u_h\|_u \leq \tilde{C} \|u - \tilde{u}_h\| \quad \forall \tilde{u}_h \in U_h$$

for where $\tilde{C} = \|S^{-1} P_{V_h} R - I\|$. ■

Further extensions: PDE. Find u st. $a(u, v) = F(v)$.

FE. Find $u_h \in U_h$ st. $a_h(u_h, v_h) = F_h(v_h) \quad \forall v_h \in V_h$.

where a_h and F_h are discretisations of a and F .

eg. if you evaluate \int_{Ω} by a quadrature rule

(See Strang's Lemma)

How to choose spectral methods for a real-world problem
Allen-Cahn eq from materials science.

$$\partial_t u - \epsilon^2 \Delta u + u^3 - u = 0$$

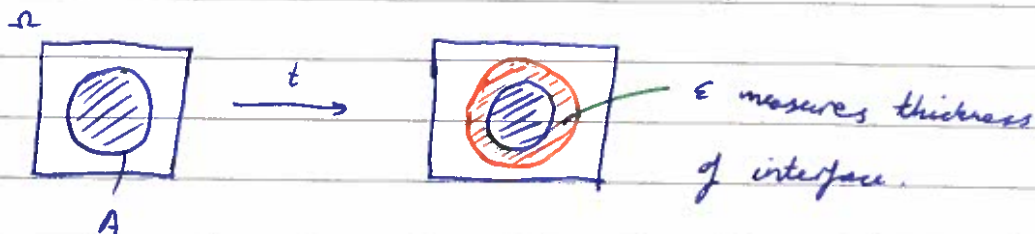
Replace by finite
difference
approx.

$u(t=0)$ given.

$$\Omega = [-1, 1]^2$$

periodic B.C.

- NOTES:
- Think of icecream melting in your mouth.
 - ϵ measures diffusion.
 - eg. initial condition $u \equiv 0$ on $\Omega \setminus A$
 $u \equiv 1$ on A



Spectral method in space.

$$u_N(x, y, t) = \sum_{k, l = -\frac{N}{2}}^{\frac{N}{2}} \tilde{u}_{k, l}(t) e^{i(kx + ly)\pi}$$

→ $(N+1)$ -dimensional ODE for $\tilde{u}(t)$.

Calling u_N^m the approx. of u_N at $t = t_m = m\Delta t$.
We would then solve the system

$$\frac{3u_N^{m+1} - 4u_N^m + u_N^{m-1}}{2\Delta t} - \epsilon^2 \Delta u_N^{m+1} + (u^3 - u)^{m+1} = 0$$

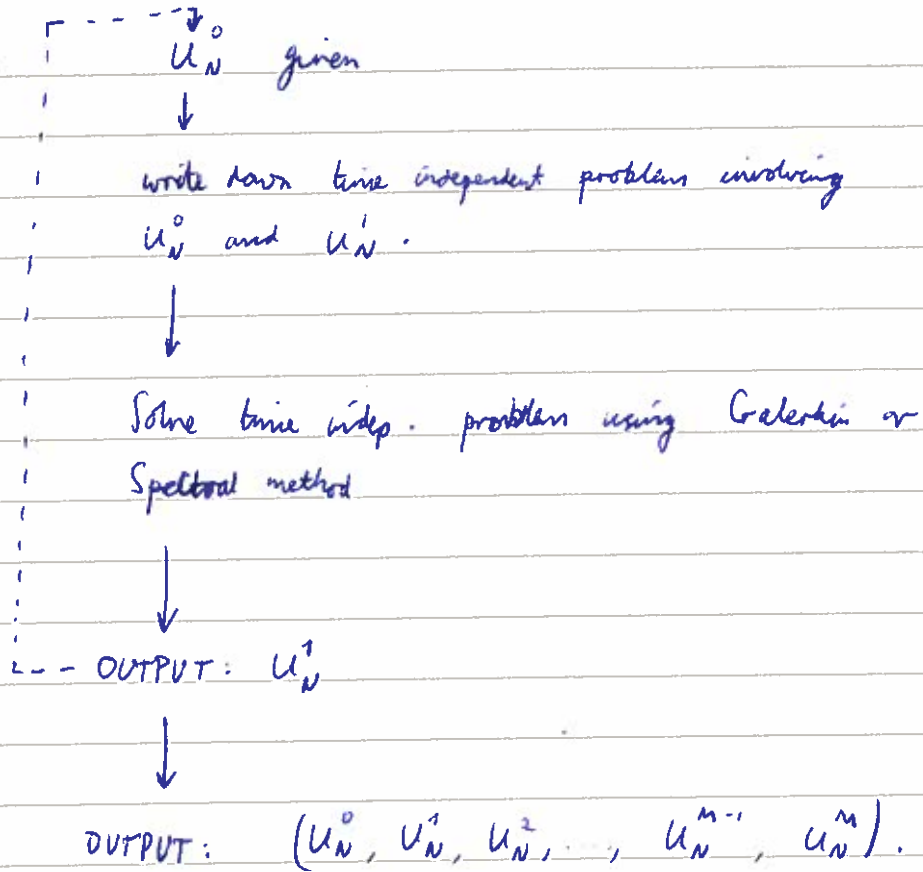
discrete time derivative

Choose u_N^1 or use
only 1st order discretisation.

If this is m then you would get a (explicit) recursion relation whereby u^{m+1} depends on $\Delta^{(m+1)} u_N^0$. Would need very strong info on initial data. Problems at high freq. With $m+1$ you make things smoother because you apply Δ^{-1} to initial data.

implicit method

Algorithm



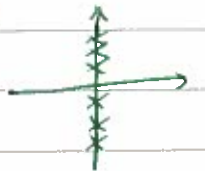
Qⁿ. What do you do with the non-linear part?
 $\sin^3(x)$ has highest frequency 3.
Need to decide what to do considering:

- facility of solution
- accuracy of solution / reliability of solⁿ.
- fast convergence at each time step / for whole scheme.

NOTE: Wave equation: $\partial_t^2 u = (\text{coercive}) u$

$$\partial_t \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ \text{coercive} & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix}$$

eigenvalues



NOT COERCIVE.