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(joint with Magnus Goffeng and Nikoletta Louca)

Oldenburg Analysis Seminar, 3 June 2021



Examples of "size"

A good notion of size satisfies:

$$Size(A \cup B) = Size(A) + Size(B) - Size(A \cap B)$$

$$Size(A \times B) = Size(A) Size(B)$$

We shall interpret these conditions very loosely...

Introduction to magnitude

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Examples of size-like notions

- Cardinality of set
- Dimension of vector space
- Measure of a measurable set
- Euler characteristic of topological space
- Intrinsic volumes of convex set (volume, surface area, total mean curvature, ...)
- Capacity in potential theory / diversity of biological system
- Magnitude

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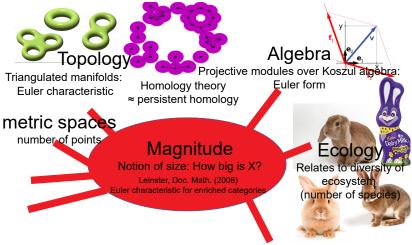
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- Capacity in potential theory / diversity of biological system
- Magnitude (Leinster '08)





Elliptic PDEs Semiclassical Analysis Geom. Measure Theory

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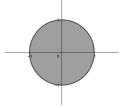
Geometry

Dim. volume, surface area, curvatures Barceló, Carbery, Amer J. Math. (2017) Gimperlein, Goffeng, Amer J. Math. (2021), + Louca (2021) Leinster, Meckes, survey article (2017)



Outline of talk

What is the magnitude of the unit disk?



- What is magnitude?
- Magnitude of compact domains X in \mathbb{R}^n and manifolds
- ullet Leinster-Willerton conjecture: geometry of $\mathcal{M}_X(R) := \max(R \cdot X)$
- Technically: semiclassical analysis of a pseudodifferential boundary problem for $(R^2 \Delta)^{\pm (n+1)/2} + l.o.t$.

Let $\mathcal{Z} \in \mathbb{R}^{n \times n}$. w weighting on \mathcal{Z} if

$$\mathcal{Z}w = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} =: \mathbf{1}.$$

Magnitude of a matrix

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Definition (Magnitude of a matrix)

If Z admits a weighting w and Z^T admits a weighting w',

$$\operatorname{mag}(\mathcal{Z}) := \sum_{i=1}^{n} w_i = \sum_{i=1}^{n} w'_i.$$

Set $mag(\mathcal{Z}) := +\infty$ otherwise.

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Check: $mag(\mathcal{Z})$ is independent of choice of weighting w, \tilde{w} :

$$\operatorname{mag}(\mathcal{Z}) = \langle w, \mathbf{1} \rangle = \langle w, \mathcal{Z}^\mathsf{T} w' \rangle = \langle \mathcal{Z} w, w' \rangle = \langle \mathcal{Z} \tilde{w}, w' \rangle = \langle \tilde{w}, \mathcal{Z}^\mathsf{T} w' \rangle = \langle \tilde{w}, \mathbf{1} \rangle$$

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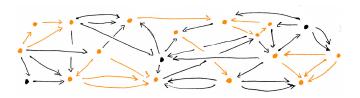
Check: $mag(\mathcal{Z})$ is independent of choice of weighting.

If \mathcal{Z} invertible, $\operatorname{mag}(\mathcal{Z}) = \langle w, \mathbf{1} \rangle = \langle \mathcal{Z}^{-1}\mathbf{1}, \mathbf{1} \rangle = \sum_{i,j} (\mathcal{Z}^{-1})_{ij}$.

Magnitude of (finite) categories and metric spaces

If C is a finite category, we set

$$\mathcal{Z}_{\mathcal{C}} := (\# \mathrm{Mor}_{\mathcal{C}}(i,j))_{i,j \in \mathrm{Obj}(\mathcal{C})}$$
 and $\mathrm{mag}(\mathcal{C}) := \mathrm{mag}(\mathcal{Z}_{\mathcal{C}}).$



(Figure by T.-D. Bradley, arxiv:1809.05923)

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Introduction to magnitude

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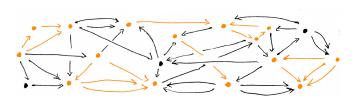
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Theorem (Leinster, original motivation for magnitude)

Let C denote a finite category and BC its classifying space, then

$$\chi(BC) = \text{mag}(C).$$

Similarly, mag recovers Euler characteristic of a triangulated manifold.



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Theorem (Leinster, original motivation for magnitude)

Let $\mathcal C$ denote a finite category and $\mathcal B\mathcal C$ its classifying space, then

$$\chi(BC) = \text{mag}(C).$$

If (X, d) is a finite metric space, category theory tells us to set

$$\mathcal{Z}_X := (e^{-d(a,b)})_{a,b \in X}$$
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Examples

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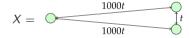
- One point space: $mag(\cdot) = 1$
- Discrete "metric" space X: mag(X) = |X|
- (Complete graph) N points, distance R:

$$\operatorname{mag}(\overbrace{\cdot \leftarrow R \to \cdot \quad \cdots \quad \cdot}) = \frac{N}{1 + (N-1)e^{-R}}$$

Example: a 3-point space (Simon Willerton)

Take the 3-point space

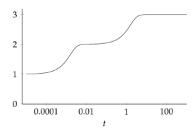
Introduction to magnitude 00000000





- When t is small, X looks like a 1-point space.
- When t is moderate, X looks like a 2-point space.
- When t is large, X looks like a 3-point space.

Indeed, the magnitude of X as a function of t is:







If (X, d) is a finite metric space, we set

$$\mathcal{Z}_X := (e^{-d(a,b)})_{a,b \in X}$$
 and $mag(X,d) := mag(\mathcal{Z}_X)$.

The magnitude function of (X, d) is given by

$$\mathcal{M}_X(R) = \max(X, R \cdot d) \qquad (R > 0) .$$

Observation

- \mathcal{M}_X extends meromorphically to $R \in \mathbb{C}$
- $\mathcal{M}_X(R) = |X| + O(R^{-\infty})$ as $R \to \infty$
- $\mathcal{M}_X(0) = 1$

(X, d) compact metric space, M(X) finite Borel measures on X.

$$\mathcal{Z}_X(R): M(X) \to C(X), \quad \mathcal{Z}_X(R)\mu(x) := \int_X e^{-Rd(x,y)} d\mu(y).$$

A weighting measure μ_R is a solution to the equation $\mathcal{Z}_X(R)\mu_R=1$ on X.

Definition / Theorem (Meckes)

Let (X, d) a positive definite compact metric space, i.e. $\mathcal{Z}_A(R)$ is a positive definite matrix for all finite $A \subseteq X$. Then

$$\mathcal{M}_X(R) := \sup \{ \mathcal{M}_A(R) : A \subseteq X \text{ finite} \}$$

If (X, d) admits a weighting measure, $\mathcal{M}_X(R) = \mu_R(X)$.

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Explicitly for
$$X \subset \mathbb{R}^n$$
, $\mathcal{Z}_X(R)f(x) := \int_{\mathbb{R}^n} \mathrm{e}^{-R|x-y|} f(y) \mathrm{d}V(y) = g_R * f(x)$, where $g_R(x) := \mathrm{e}^{-R|x|}$. With $\hat{g}_R(\xi) = n! \omega_n R(R^2 + |\xi|^2)^{-(n+1)/2}$,

$$\mathcal{Z}_X(R) = n!\omega_n R(R^2 - \Delta)^{-(n+1)/2}.$$

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The function $h := \mathcal{Z}_X(R)\mu_R$ extends to \mathbb{R}^n , with h = 1 on X.

Theorem (Meckes)

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$$\mathcal{M}_{X}(R) = \frac{1}{n!\omega_{n}R} \inf \left\{ \| (R^{2} - \Delta)^{(n+1)/4} h \|_{L^{2}(\mathbb{R}^{n})}^{2} : h \in H^{(n+1)/2}(\mathbb{R}^{n}), \ h = 1 \text{ on } X \right\}$$
$$= \frac{1}{n!\omega_{n}R} \| (R^{2} - \Delta)^{(n+1)/4} h \|_{L^{2}(\mathbb{R}^{n})}^{2}$$

where $h \in H^{(n+1)/2}(\mathbb{R}^n)$ solves

$$(R^2 - \Delta)^{(n+1)/2} h = 0$$
 weakly in $\mathbb{R}^n \setminus X$, $h = 1$ on X .

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Theorem (Meckes)

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Example

$$X = [-1, 1] \subset \mathbb{R}$$
. $\mathcal{M}_X(R) = 1 + R = \chi(X) + \frac{\text{Length}(X)}{2}R$.

Geometry of the magnitude function

Conjecture (Leinster, Willerton)

Let $X \subseteq \mathbb{R}^n$ be a compact convex subset. Then

$$\mathcal{M}_X(R) = \sum_{k=0}^n \frac{V_k(X)}{k!\omega_k} R^k$$
.

Here $V_k(X)$ is the k-th intrinsic volume of X, ω_k volume of unit ball in \mathbb{R}^k .

For X a smooth convex body: $V_n(X) = \operatorname{vol}_n(X)$, $V_{n-1}(X) = \operatorname{vol}_{n-1}(\partial X)$, $V_{n-2}(X) = \int_{a_X} H dS, ..., V_0(X) = \chi(X).$

Special cases:

$$n = 1: \mathcal{M}_X(R) = \chi(X) + \frac{\text{Length}(X)}{2} R.$$

$$n=2$$
: $\mathcal{M}_X(R)=\chi(X)+rac{\mathrm{Perim}(\partial X)}{4}R+rac{\mathrm{Area}(X)}{2\pi}R^2$.

The conjecture was motivated by computational examples, the historical analogy with the Euler characteristic, and Hadwiger's theorem.

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Consequences include: Inclusion-Exclusion principle

$$\mathcal{M}_{A\cup B} = \mathcal{M}_A + \mathcal{M}_B - \mathcal{M}_{A\cap B}$$
.

Conjecture true for $X \subset \mathbb{R}$

$$X = [-1,1] \subset \mathbb{R}$$
. $\mathcal{M}_X(R) = 1 + R = \chi(X) + \frac{\text{Length}(X)}{2}R$.

Leinster-Willerton conjecture: (Counter) Examples

Barcelo, Carbery 2017 prove the conjectured behaviour for $R \to \infty$ and $R \to 0$:

Theorem

Let $X \subseteq \mathbb{R}^n$ be a compact smooth domain. Then

$$\mathcal{M}_X(R) = rac{\mathrm{vol}(X)}{n!\omega_n}R^n + o(R^n), \ ext{as } R o \infty,$$

$$\lim_{R\to 0}\mathcal{M}_X(R)=1.$$

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Furthermore, they solve the magnitude PDE for $X=B(0,1)\subseteq\mathbb{R}^n$, n=5:

$$\mathcal{M}_X(R) = \frac{1}{n!\omega_n R} \| (R^2 - \Delta)^{(n+1)/4} h \|_{L^2(\mathbb{R}^n)}^2$$

where $h \in H^{(n+1)/2}(\mathbb{R}^n)$ satisfies

$$(R^2 - \Delta)^{(n+1)/2} h = 0$$
 weakly in $\mathbb{R}^n \setminus X$, $h = 1$ on X .

The result is

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$$\mathcal{M}_X(R) = rac{\mathrm{vol}(X)}{n!\omega_n}R^n + o(R^n), \text{ as } R o \infty,$$

$$\lim_{R o 0} \mathcal{M}_X(R) = 1.$$

Counterexample to Leinster-Willerton conjecture (Barcelo, Carbery 2017)

Let $X = B(0,1) \subseteq \mathbb{R}^5$ be the unit ball. Then

$$\mathcal{M}_X(R) = \frac{R^5}{5!} + \frac{3R^5 + 27R^4 + 105R^3 + 216R^2 + 72}{24(R+3)}$$

Not a polynomial. Also coefficients of R^k wrong.

Willerton obtains similar rational functions for balls in odd dimensions.

With M. Goffeng, we studied the magnitude PDE for general X, n odd:

$$(R^2 - \Delta)^{(n+1)/2}h = 0$$
 weakly in $\mathbb{R}^n \setminus X$, $h = 1$ on X .

Using Green's formula, for suitable boundary traces $\mathcal{D}_R^k h|_{\partial X}$ of order k:

$$\mathcal{M}_{X}(R) = \frac{1}{n!\omega_{n}R} \| (R^{2} - \Delta)^{(n+1)/4} h \|_{L^{2}(\mathbb{R}^{n})}^{2}$$

$$= \frac{\text{vol}_{n}(X)}{n!\omega_{n}} R^{n} - \frac{1}{n!\omega_{n}} \sum_{\frac{m}{2} < j \le m} R^{n-2j} \int_{\partial X} \mathcal{D}_{R}^{2j-1} h \, dS$$

$$= \frac{\text{vol}_{n}(X)}{n!\omega_{n}} R^{n} - \frac{1}{n!\omega_{n}} \sum_{\frac{m}{2} < j \le m} R^{n-2j} \int_{\partial X} \Lambda_{2j-1}(R) \, 1 \, dS.$$

The Λ_k are components of an $m \times m$ Dirichlet-to-Neumann operator, a parameter-elliptic pseudodifferential operator on ∂X , meromorphic in R. Analytic Fredholm theory and an explicit symbol computation show:

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Theorem (Gimperlein, Goffeng, Amer J Math 2021 $+\epsilon$)

Let $X \subseteq \mathbb{R}^n$ be compact with smooth boundary and n = 2m - 1.

- \mathcal{M}_X extends meromorphically to \mathbb{C} .
- \mathcal{M}_X holomorphic in sector $\{|\arg(z)| < \frac{\pi}{n+1}\}$. Finite number of poles in any sector $\{|\arg(z)| < \alpha\}, \ \alpha < \frac{\pi}{2}.$

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- There are constants $(c_k(X))_{k\in\mathbb{N}}$ such that for all $N\in\mathbb{N}$

$$\mathcal{M}_X(R) = \frac{1}{n!\omega_n} \sum_{k=0}^{n+N} c_k(X) R^{n-k} + O(R^{-N}).$$

The first four coefficients are given by

$$\begin{split} c_0(X) &= \mathrm{vol}_n(X), \ c_1(X) = m \mathrm{vol}_{n-1}(\partial X), \\ c_2(X) &= \frac{m^2}{2} \ (n-1) \int_{\partial X} H \, dS, \qquad (H \text{ mean curvature of } \partial X) \\ c_3(X) &= \alpha_n \int_{\partial X} H^2 \, dS \qquad (Willmore energy) \end{split}$$

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The first four coefficients are given by

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 $c_2(X) = \frac{m^2}{2} (n-1) \int_{\partial Y} H \, dS, \qquad c_3(X) = \alpha_n \int_{\partial Y} H^2 \, dS$

• For $j \ge 4$, the coefficient $c_j(X)$ is an integral over ∂X of a universal polynomial in covariant derivatives of the fundamental form of total order j-2 and total degree j-1.

Corollaries

Asymptotic inclusion-exclusion

Let n=2m-1. If $A,B\subseteq\mathbb{R}^n$, as well as $A\cup B$ and $A\cap B$ are smooth compact domains then

$$\mathcal{M}_{A \cup B}(R) = \mathcal{M}_A(R) + \mathcal{M}_B(R) - \mathcal{M}_{A \cap B}(R) + O(R^{-\infty}).$$

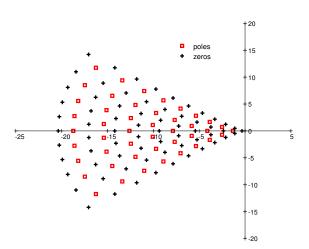
Definite failure of original Leinster-Willerton conjecture

The coefficient $c_3(X) = \alpha_n \int_{\partial X} H^2 \mathrm{d}S$ is not Hausdorff continuous and not an intrinsic volume. Indeed, for n=3 by homogeneity $c_3(X)$ would need to be proportional to the Euler characteristic. But c_3 = Willmore energy can be made arbitrarily large on surfaces of genus zero.

Can you "magnitude" the shape of a drum?

Let X as in theorem, B ball. If $\mathcal{M}_X \sim \mathcal{M}_B$, then X is isometric to B (use asymptotics & isoperimetric inequality).

There are nonconvex domains X, Y = balls with a hole which are not isometric, but $\mathcal{M}_X = \mathcal{M}_Y$ (Meckes).



Poles and zeros of \mathcal{M}_{B_n} in dimensions n=13,17,21

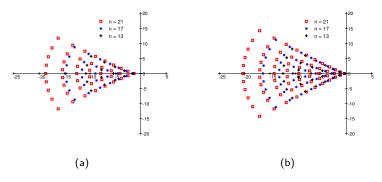
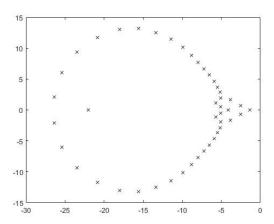
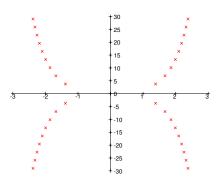


Figure: (a) poles, (b) zeros.

Computer algebra delicate: Naive computation of poles of $\mathcal{M}_{B_{21}}$ (with Maple, Sage)



 $X = (2B_3) \setminus B_3^{\circ}$



infinite number of poles approaching curve $|Re(R)| = \log(|Im(R)|)$

$$\mathcal{M}_X(R) = \frac{7}{6}R^3 + 5R^2 + 2R + 2 + \frac{e^{-2R}(R^2 + 1) + 2R^3 - 3R^2 + 2R - 1)}{\sinh(2R) - 2R}$$

Theorem (Gimperlein, Goffeng, Amer J Math 2021 $+\epsilon$)

Let $X \subseteq \mathbb{R}^n$ be compact with smooth boundary and n = 2m - 1.

- \mathcal{M}_X extends meromorphically to \mathbb{C} .
- \mathcal{M}_X holomorphic in sector $\{|\arg(z)| < \frac{\pi}{n+1}\}$. Finite number of poles in any sector $\{|\arg(z)| < \alpha\}$, $\alpha < \frac{\pi}{2}$.
- There are constants $(c_k(X))_{k\in\mathbb{N}}$ such that for all $N\in\mathbb{N}$

$$\mathcal{M}_X(R) = \frac{1}{n!\omega_n} \sum_{k=0}^{n+N} c_k(X) R^{n-k} + O(R^{-N}).$$

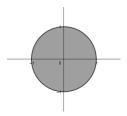
The first four coefficients are given by

$$c_0(X) = \operatorname{vol}_n(X), \ c_1(X) = m \operatorname{vol}_{n-1}(\partial X),$$
 $c_2(X) = \frac{m^2}{2} (n-1) \int_{\partial X} H \, dS, \qquad c_3(X) = \alpha_n \int_{\partial X} H^2 \, dS$

• For $j \ge 4$, the coefficient $c_j(X)$ is an integral over ∂X of a universal polynomial in covariant derivatives of the fundamental form of total order j-2 and total degree j-1.

What is the magnitude of the unit disk?

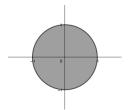
In even dimensions almost nothing has been known about magnitude.



$$\mathcal{M}_{B_2(0,1)}(R) = ?$$

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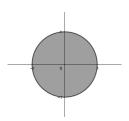


Theorem (Gimperlein, Goffeng, Louca 2021)

$$\mathcal{M}_{B_2(0,1)}(R) = \frac{1}{2}R^2 + \frac{3}{2}R + O(1)$$

More generally, we extend the previous statements on the meromorphic continuation and asymptotic expansion of \mathcal{M}_X to smooth compact domains $X \subset M$, where $M = \mathbb{R}^n$ or (under technical assumptions) M manifold with metric.

In even dimensions almost nothing has been known about magnitude.



Theorem (Gimperlein, Goffeng, Louca 2021)

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• Study directly the boundary problem for $\mathcal{Z}_X(R) = (R^2 - \Delta)^{-(n+1)/2}$:

$$\mathcal{Z}_X(R)\mu_R = 1$$
 in X , supp $\mu_R \subseteq X$.

• Analysis relies on ideas of Hörmander, Eskin, as recently developed by Grubb for fractional boundary problems involving $(-\Delta)^s$, s > 0.



- $X \subseteq \mathbb{R}^n$ compact domain with smooth boundary (more generally: $X \subseteq \mathbb{R}^N$ compact submanifold with boundary).
- Consider the operator

$$\tilde{\mathcal{Z}}_X(R)f(x) = \frac{1}{R}\mathcal{Z}_X(R)f(x) = \frac{1}{R}\int_X e^{-Rd(x,y)}f(y) \ dV(y)$$

• For $s \in \mathbb{R}$:

$$\begin{split} &H^{\mathfrak{s}}(\mathbb{R}^{n}) := \{u : (1 + |\xi|^{2})^{\mathfrak{s}/2} \hat{u} \in L^{2}(\mathbb{R}^{n})\}; \\ &\mathring{H}^{\mathfrak{s}}(X) := \{u \in H^{\mathfrak{s}}(\mathbb{R}^{n}) : \operatorname{supp}(u) \subseteq X\}; \\ &\bar{H}^{\mathfrak{s}}(X) := H^{\mathfrak{s}}(\mathbb{R}^{n}) / \mathring{H}^{\mathfrak{s}}(\mathbb{R}^{n} \setminus X) = \{u | x : u \in H^{\mathfrak{s}}(\mathbb{R}^{n})\}. \end{split}$$

• $\mathring{H}^0(X) = \overline{H}^0(X) = L^2(X)$ and the L^2 -pairing extends to a perfect pairing

$$\mathring{H}^s(X) \times \bar{H}^{-s}(X) \to \mathbb{C}.$$

Some facts

- $\tilde{Z}_X(R)$ is a parameter-elliptic pseudodifferential operator of order -n-1.
- $\tilde{\mathcal{Z}}_X(R): \mathring{H}^{-(n+1)/2}(X) \to \bar{H}^{(n+1)/2}(X)$ is a continuous isomorphism for $\operatorname{Re}(R) \gg 0$, which extends to a holomorphic Fredholm operator valued function of $R \in \mathbb{C}$.
- Fredholm theory: $\tilde{\mathcal{Z}}_X(R)^{-1}: \bar{H}^{(n+1)/2}(X) \to \mathring{H}^{-(n+1)/2}(X)$ extends meromorpically to $R \in \mathbb{C}$. It is "computable" up to $O(R^{-\infty})$.
- The function $h \in H^{(n+1)/2}(\mathbb{R}^n)$ defined from

$$h(x) := R^{-1} \int_X e^{-R|x-y|} (\tilde{\mathcal{Z}}_X(R)^{-1} 1_X)(y) dV(y),$$

solves Meckes' minimization problem, so that

$$\mathcal{M}_X(R) = R^{-1}(\tilde{\mathcal{Z}}_X(R)^{-1}1_X, 1_X)_{L^2}.$$

The magnitude function thus extends meromorphically to $R \in \mathbb{C}$.



Construction of asymptotic expansions

Theorem (Gimperlein-Goffeng-Louca '21)

Let $X \subseteq \mathbb{R}^n$ be a compact domain with smooth boundary. Then

$$\mathcal{M}_X(R) = \frac{1}{n!\omega_n} \sum_{k=0}^{\infty} c_k(X) R^{n-k} + O(R^{-\infty}).$$

The first three coefficients are given by

$$c_0(X) = \operatorname{vol}_n(X), \ c_1(X) = \gamma_{n,1} \operatorname{vol}_{n-1}(\partial X), \ c_2(X) = \gamma_{n,2} \int_{\partial X} H dS,$$

where H is the mean curvature. There exists an iterative way of computing the coefficients $c_k(X)$.

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- Iterative scheme is a result of a Wiener-Hopf factorization using a 'nice' factorization of the symbol.
- The result holds for $X \subseteq \mathbb{R}^N$ a compact submanifold with boundary, and in this case

$$c_k(X) = \int_X \alpha_k(x) dV(x) + \int_{\partial X} \beta_k(x) dS(x),$$

and $\alpha_k = 0$ for all odd k.

There is an iterative scheme to compute α_k and β_{k}

The idea for $X \subseteq \mathbb{R}$

Consider $X=[0,1]\subseteq\mathbb{R}$ so we are looking for a $u\in\mathring{H}^{-1}(0,1)$ with

$$\mathcal{Z}_X(R)u(x) = \int_0^1 e^{-R|x-y|} u(y) dy = 1.$$

Fourier transforming gives

$$\mathcal{F}(\mathcal{Z}_X(R)u)(\xi) = 2R(R^2 + \xi^2)^{-1}\hat{u}(\xi) = 2R(R + i\xi)^{-1}(R - i\xi)^{-1}\hat{u}(\xi).$$

Elementary computations give

$$\begin{cases} (R+i\xi)^{-1} = \mathcal{F}(z_R^+), & z_R^+(x) = \chi_{[0,\infty)}(x)e^{-Rx} \\ (R-i\xi)^{-1} = \mathcal{F}(z_R^-), & z_R^-(x) = \chi_{(-\infty,0]}(x)e^{Rx} \end{cases}$$

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Paley-Wiener!

Consider $\mathcal{Z}_X(R)^{\pm}f := z_R^{\pm} * f$.



The idea for $X \subseteq \mathbb{R}$, continued

Introduction to magnitude

The operators $\mathcal{Z}_X(R)^{\pm}f:=z_R^{\pm}*f$ satisfy for any $a\in\mathbb{R}$:

$$\begin{cases} \operatorname{supp}(f) \subseteq [a, \infty) \Rightarrow \operatorname{supp}(\mathcal{Z}_X(R)^+ f) \subseteq [a, \infty), \\ \operatorname{supp}(f) \subseteq (-\infty, a] \Rightarrow \operatorname{supp}(\mathcal{Z}_X(R)^- f) \subseteq (-\infty, a]. \end{cases}$$

Therefore, for any real s and a, $\mathcal{Z}_X(R)^{\pm}$ defines isomorphisms

$$\begin{cases} \mathcal{Z}_X(R)^+ : \mathring{H}^s(a,\infty) \to \mathring{H}^{s+1}(a,\infty), \ \mathcal{Z}_X(R)^+ : \overline{H}^s(-\infty,a) \to \overline{H}^{s+1}(-\infty,a), \\ \mathcal{Z}_X(R)^- : \mathring{H}^s(-\infty,a) \to \mathring{H}^{s+1}(-\infty,a), \ \mathcal{Z}_X(R)^- : \overline{H}^s(a,\infty) \to \overline{H}^{s+1}(a,\infty). \end{cases}$$

Problem arising in the general setting

How to factor $\mathcal{Z}_X(R): \mathring{H}^{-1}(0,1) \to \overline{H}^1(0,1)$ near ∂X as mapping

$$\mathring{H}^{-1}(0,1) \xrightarrow{\mathcal{Z}_{X,+}(R)} \mathring{H}^{0}(0,1) = L^{2}(0,1) = \overline{H}^{0}(0,1) \xrightarrow{\mathcal{Z}_{X,-}(R)} \overline{H}^{1}(0,1)?$$

Structure of inverse operator

$$\mathcal{Z}_X(R)^{-1} = \tilde{\chi}_1 Q^{-1} \chi_1 + \tilde{\chi}_2^{-1} \mathcal{Z}_{X,+}(R)^{-1} \mathcal{Z}_{X,-}(R)^{-1} \chi_2 + S$$

where χ_j gluing functions, Q^{-1} interior parametrix, $S = O(R^{-\infty})$.

The idea for $X \subseteq \mathbb{R}$, continued

Formally, $(\mathcal{Z}_X(R)^{\pm})^{-1} = R \pm \partial_x$. Is it simply that

$$\mathcal{Z}_X(R)^{-1}f = \frac{1}{2R}(R + \partial_x)(R - \partial_x)f$$
?

For $f = 1_{[0,1]} \in \overline{H}^1(0,1)$, then

$$\frac{1}{2R}(R+\partial_x)(R-\partial_x)1_{[0,1]} = \frac{1}{2R}(R+\partial_x)(\underbrace{R1_{[0,1]}}_{\in \mathring{H}^0(0,1)}) = \frac{R}{2}1_{[0,1]} + \frac{1}{2}(\delta_{x=1} - \delta_{x=0}).$$

But we have that

$$\mathcal{Z}_X(R)\left(\frac{R}{2}\mathbf{1}_{[0,1]} + \frac{1}{2}(\delta_{x=1} - \delta_{x=0})\right) = 1 - e^{-R(1-x)},$$

It does not hold that $e^{-R(1-x)} = O(R^{-\infty})$ in norm sense on $\overline{H}^1(0,1)!$ The correct answer is

$$\mathcal{Z}_X(R)^{-1}1_{[0,1]} = \frac{R}{2}1_{[0,1]} + \frac{1}{2}(\delta_{x=1} + \delta_{x=0}).$$

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To fix the sign mistake: build $\mathcal{Z}_{X,+}(R)^{-1}$ from gluing $(\mathcal{Z}_X(R)^{\pm})^{-1}$ at x=0 with $(\mathcal{Z}_X(R)^{\mp})^{-1}$ at x=1... Morally we have that

$$\mathcal{Z}_X(R)^{-1}=rac{1}{2R}(R+\partial_x)(R-\partial_x)$$
 at $x=1$, $\mathcal{Z}_X(R)^{-1}=rac{1}{2R}(R-\partial_x)(R+\partial_x)$ at

Extension to manifolds

Compact, smooth $X \subseteq M$ for d satisfying a technical assumption, e.g.

- M is a sphere with geodesic distance
- M is a Riemannian manifold with geodesic distance and diam(X) < inj(M)
- M is a submanifold of \mathbb{R}^n with the subspace metric

For large R, $\tilde{\mathcal{Z}}_R = n!\omega_n(R^2 - \Delta)^{-\frac{n+1}{2}} + \text{l.o.t}(R, \text{derivatives})$

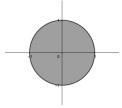
Some open analytic problems for magnitude

- For general Riemannian manifolds an improved understanding of the cut-locus seems required.
- The magnitude function for domains with edges: $\mathcal{M}_{X\cap Y}$?
- Poles of \mathcal{M}_X analogous to scattering resonances. Interpretation: Why is there a pole at R=-3 for $B(0,1)\subset\mathbb{R}^5$? Counting: Sharp upper and lower bounds? Does a generic perturbation of $B(0,1)\subset\mathbb{R}^{2m-1}$ have infinitely many poles?
- Geometric interpretation of the Taylor coefficients for \mathcal{M}_X at R=0? Meckes (2020) proves *upper bounds* in terms of intrinsic volumes.

Magnitude is just one example of a semiclassical pseudodifferential boundary problem. Related questions arise for log-gases, random matrices, optimal placement problems, . . .

At beginning of talk I asked:

What is the magnitude of the unit disk?



This talk: qualitative properties and semiclassical limit for large radius.

Can one find an exact formula for the solution of the boundary problem for $(1-\Delta)^{3/2}$ outside the disk?

Thank you for your attention!

More details in: arXiv:1706.06839 and more to come very soon

Magnitude bibliography: maths.ed.ac.uk/~tl/magbib